1. (Once Amended) An apparatus for [retrieval of] <u>manipulating</u> storage units [from] <u>in</u> a library, the apparatus comprising:

a first center column having a first arm with first and second ends wherein the first end of said first arm is attached to said first center column and said first arm extends substantially radially outward from said first center column;

a first hand attached to the second end of said first arm for manipulating storage units from the library;

a second center column having a second arm with first and second ends wherein the first end of the second arm is attached to the second center column and said second arm extends substantially radially outward from said second center column; and

a second hand attached to the second end of said second arm for manipulating storage units from the library; wherein

said first arm and said second arm rotate about a same vertical axis of rotation; and

each arm and hand is independently moveable from the other arm and hand.

22. (Once Amended) A data storage and retrieval system adapted to operate within a library service module having an array of cells configured to receive data storage units, the system comprising:

a first robot unit, wherein the first robot unit transports a data storage unit to and from the array of cells; and

a second robot unit, located within the [polygonal] array of cells, wherein the second robot unit, independently with respect to the first robot unit, manipulates data storage units placed in the array of cells.